

The Multi-angle Polarimeter

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AOS Reviewed – Not Subject to Export Control

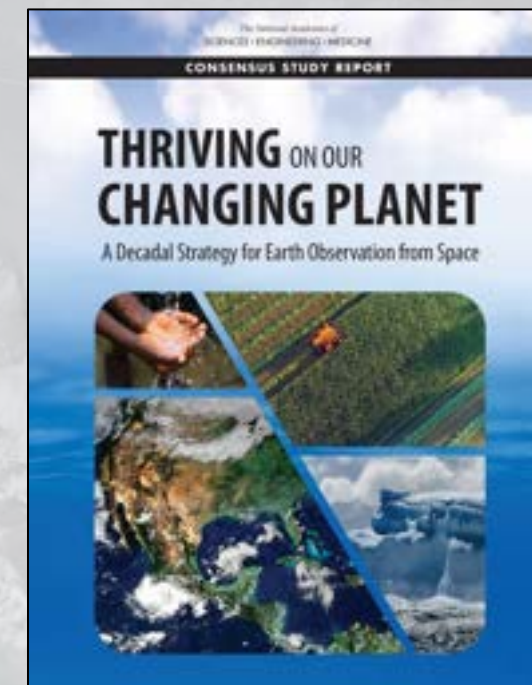
Decadal Survey Recommendations



Targeted Observable	Science/Applications Summary	Candidate Measurement Approach
Aerosols	Aerosol properties, aerosol vertical profiles, and cloud properties to understand their effects on climate and air quality	Backscatter lidar and multichannel/multiangle/polarization imaging radiometer flown together on the same platform
Clouds, Convection, and Precipitation	Coupled cloud-precipitation state and dynamics for monitoring global hydrological cycle and understanding contributing processes including cloud feedback	Dual-frequency radar, with multifrequency passive microwave and sub-mm radiometer

Mentioned together

Targeted Observable	Added Measurement Considerations	Notes
Aerosols	Ocean Ecosystem capability	HSRL desirable but possibly beyond cost cap
Clouds, Convection and Precipitation	Diurnal cycle characterization assisted by Program of Record (PoR)	Minimum capability of single frequency radar with dynamics (Doppler or proxy)



National Academies of Sciences, Engineering, and Medicine 2018

Decadal survey + ACCP studies recommended:

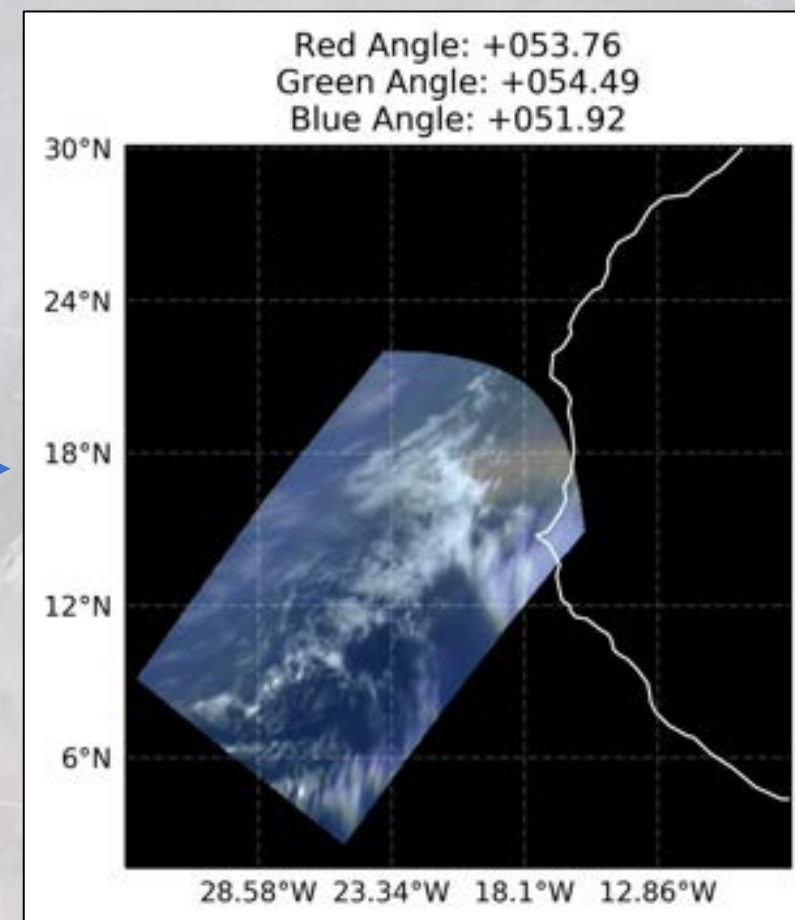
Passive radiometer with measurement characteristics

- multi-spectral (UV-VIS-NIR-SWIR)
- multi-angle / hyper-angle (10-60 views per pixel)
- accurate polarization sensitivity

Animation through
multi-angle views

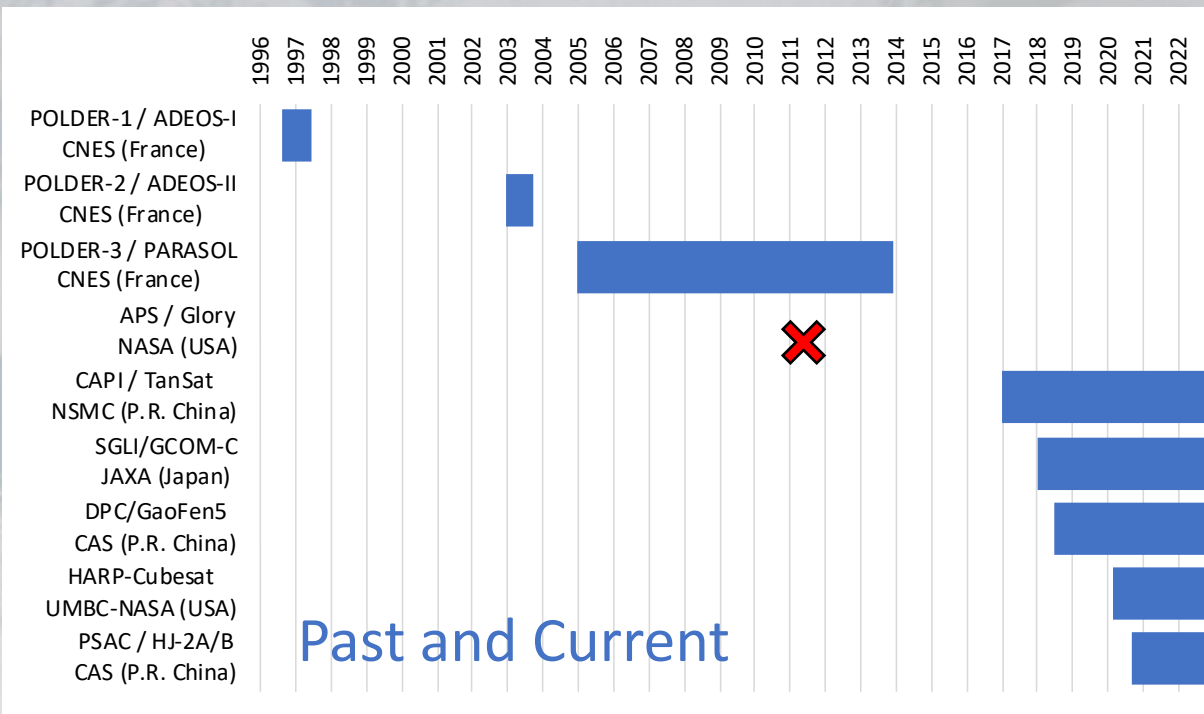
Addresses climate, weather and air quality objectives
with measurements of **cloud** and **aerosol** properties

HARP Cubesat RGB imagery, West Africa with
Saharan dust, glint, clouds 2020 / 06 / 13



Not shown are hyperangle and polarimetric data. The AOS
polarimeter would have UV, SWIR and better spatial resolution.
From: <https://esi.umbc.edu/hyper-angular-rainbow-polarimeter/>

History of Multi-Angle Polarimeters



Multi-angle polarimeters in LEO

POLDER-3 – arguably most successful polarimeter to date.

APS/Glory – NASA’s attempt at a polarimeter ended in a launch failure

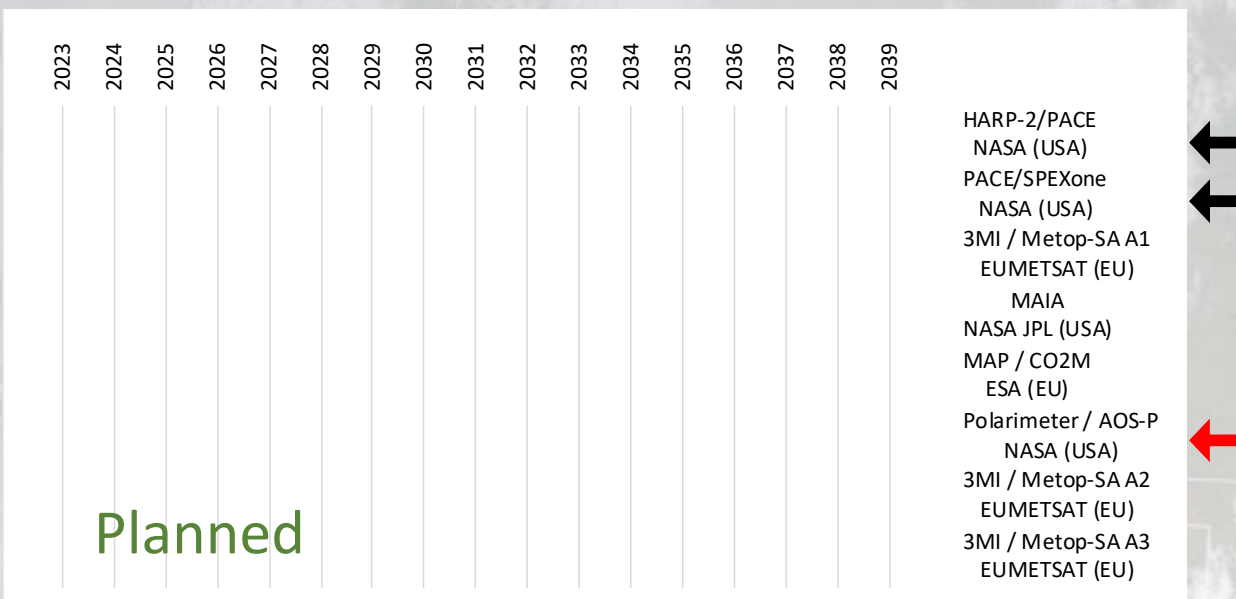
PACE/HARP2 and **PACE/SPEXone** – ‘do no harm’ instruments, proof of concept

HARP-Cubesat and **MAIA** – US instruments that (did/will) lack global coverage

AOS will improve upon POLDER with better cloud measurements (SWIR channels and polarimetric approach), order of magnitude better accuracy and UV for aerosols, and parallax-based feature height detection capability. **It will be NASA’s contribution to global measurement of aerosols and clouds.**

From:
 Dubovik et al. : Polarimetric remote sensing of atmospheric aerosols: Instruments, methodologies, results, and perspectives, J. Quant. Spectrosc. Ra., 224, 474 - 511 , <https://doi.org/10.1016/j.jqsrt.2018.11.024> , 2019.

Advancement of POLarimetric Observations (APOLO-2022) conference presentations: <https://pikesmeetings.wixsite.com/apolo-2022>



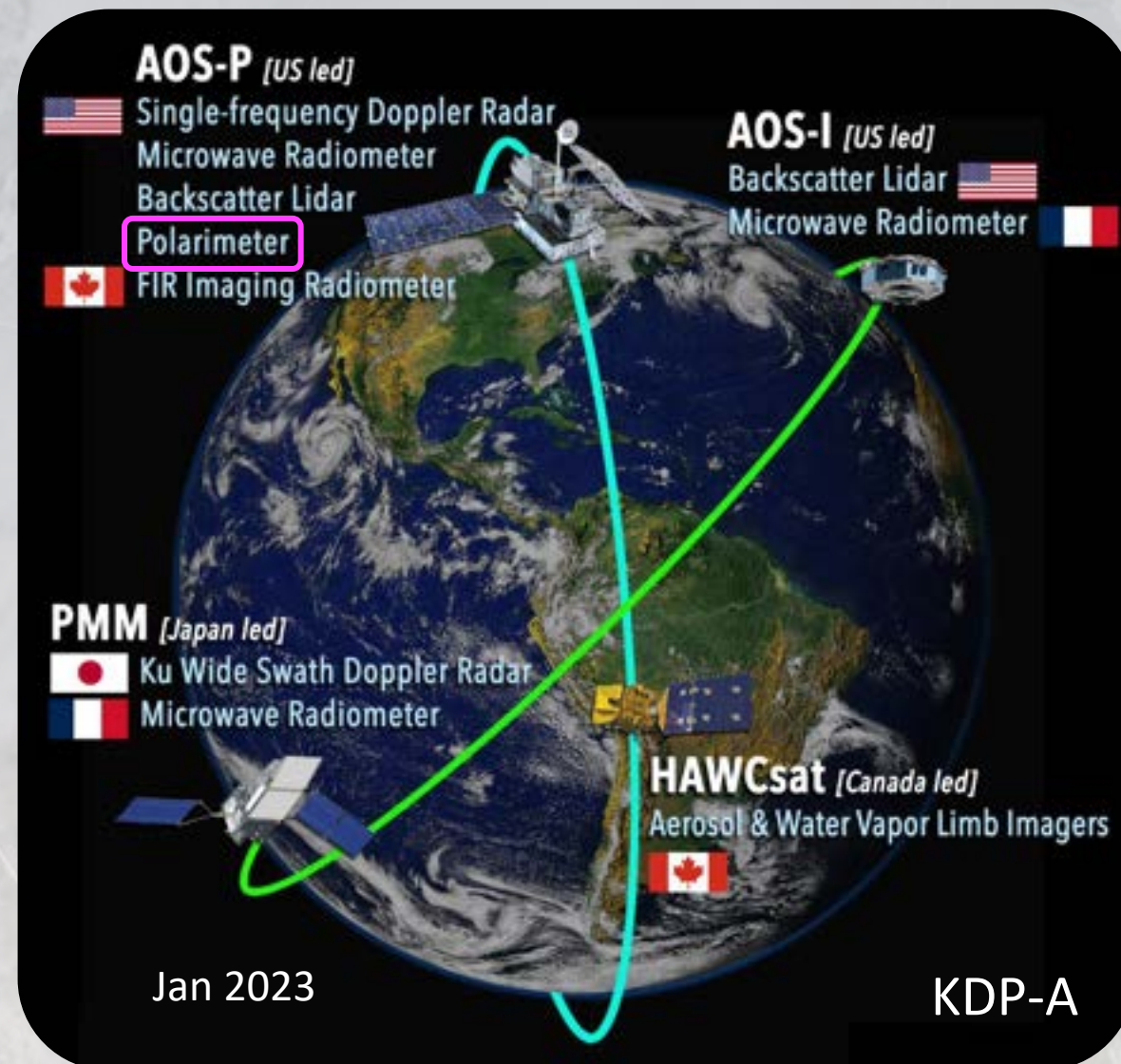
KDP-A Architecture

The original ACCP Architecture called for a polarimeter in AOS-P and AOS-I

The AOS-I polarimeter was descoped prior to MCR along with other instruments

Some AOS-P polarimeter requirements (SWIR channels) were strengthened to enable a portion of measurements lost with the SW Spectrometer descope

AOS intends a procurement through open competition



(Current) Requirements



Summary of instrument requirements:

Spatial resolution of 500m at **nadir**, cross track swath of 300km

Total uncertainty: radiometric < 3%, Degree of Linear Polarization (DoLP) < 0.005

Science driver	Wavelength range	# of bands	# of viewing angles per pixel
Aerosol	UV: 350 – 390 nm	1	10
Aerosol, bi-spectral cloud	VIS-NIR: 410 – 750 nm	2	10
Cloudbow cloud retrieval	Hyperangle: 670 – 870 nm	1	60
Water vapor measurement	NIR: 900 – 960nm	1	10
SWIR cirrus cloud detection	SWIR: 1350 – 1400nm	1	10
Aerosol, bi-spectral cloud	VNIR-SWIR: 870 – 1570 nm	3	10

Multi-angle, polarimetric measurements for all channels

Multiple retrieval categories

Aerosol: multiangle, polarimetric UV-VIS-NIR observations to determine **aerosol optical depth** and **aerosol microphysical properties**.

Bi-spectral Cloud: pairs of NIR/SWIR channels to determine **cloud optical depth** and **droplet effective radius**

Cloudbow Cloud: hyperangle polarimetric VIS/NIR observations to determine **cloud optical depth** and **droplet effective radius and variance**.

Water vapor channel to characterize water vapor profile applied to correct water vapor response in other channels

Cirrus cloud detection channel in strong water absorption feature to detect thin cirrus clouds that impact other retrievals

Unique and important capability



Polarimeter Traceability Matrix: Clouds



Thresholds indicated by [brackets]

Science Objectives	Geophysical Variable Requirements		Observables	Measurements		Instrument	
	Geophysical Variable	Conditions		Requirements	Projected Performance	Requirements	Projected Performance*
O1. Low Clouds O2. High Clouds O4. Cold clouds and precipitation	GV5. Cloud droplet effective radius O1, O6, O8	Daytime , low cloud (<5km top) Uncertainty: 50% for precipitating clouds, 20% otherwise Range: optical depth > 2, effective radius 5-30 μ m Resolution: 500m [1km] nadir Swath: 300km [100km]	Passive bi-spectral (NIR, SWIR) radiance pairs Bispectral method	Spectral: 1 NIR, 1 SWIR at 2250 [1600] nm	NIR-SWIR: 870, 940, 1230, 1380, 1570 NIR exceeds baseline	Resolution: 500m [1km] at nadir	MegaHARP-4: 0.5km Meets baseline MegaHARP-2: 1km Meets threshold
				View angles: 10 view angles within $\pm 57^\circ$ along track for all channels except 660nm, which has 60 view angles	Swath: 300km [100km]	MegaHARP-4: 394km Exceeds baseline MegaHARP-2: 1008km Exceeds baseline	
O6. Aerosol removal, vertical redistribution, and processing O8. Aerosol indirect effect	GV7. Cloud optical depth O1, O2, O4, O6, O8	Daytime Uncertainty: max(0.3, 50%) Range: 0.3 < optical depth < 50 Resolution: 1km nadir	Passive hyper-angle view polarization Rainbow method	Spectral: 1 NIR hyper-angle	NIR hyperangle: 660 meets baseline	Resolution: 500m [1km] at nadir	MegaHARP-4: 394km Exceeds baseline MegaHARP-2: 1008km Exceeds baseline
View angles: 10 view angles within $\pm 57^\circ$ along track for 660nm channel				Swath: 300km [100km]	MegaHARP-4: 394km Exceeds baseline MegaHARP-2: 1008km Exceeds baseline		

Daytime measurements of:

GV5: cloud droplet size

GV7: optical depth

at 500m nadir resolution and 300km swath (baseline) - important for 5 science objectives

The polarimeter has two independent ways to determine these properties; these products have different vertical sensitivity

* Projected performance is for industry study instruments MegaHARP-4 and MegaHARP-2; polarimeter contract will be awarded in Phase B

Bispectral (Nakajima-King) heritage algorithms use NIR/SWIR spectral pairs

Lookup table for liquid phase cloud

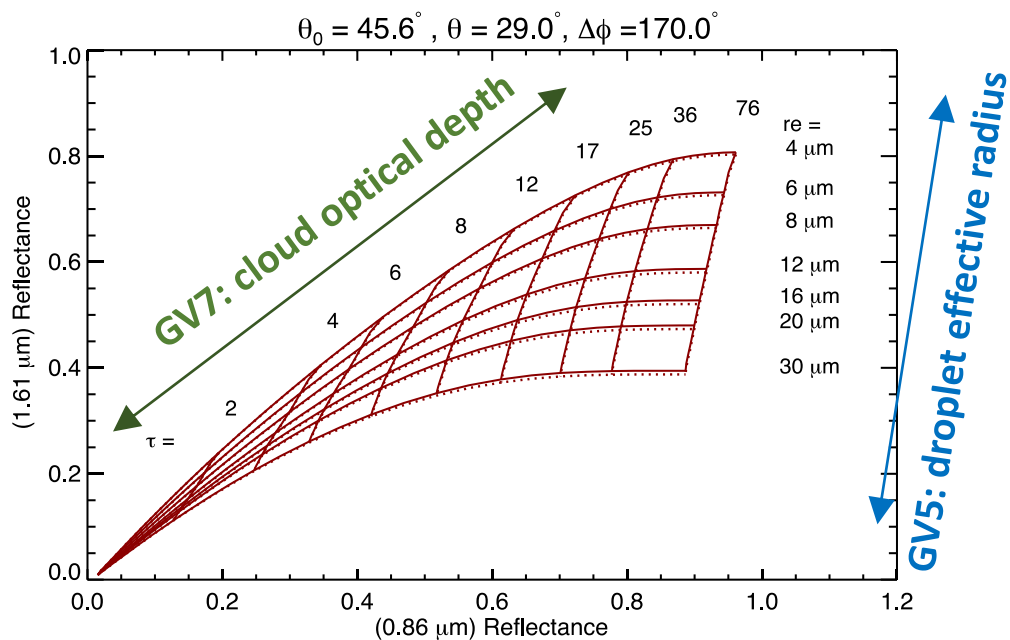
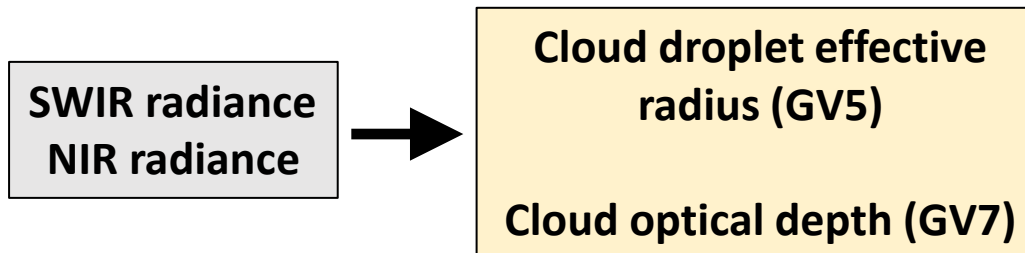


Figure courtesy of Kerry Meyer, NASA GSFC



Details:

Sensitive to body of cloud , assumes droplet effective variance, no aerosols above clouds

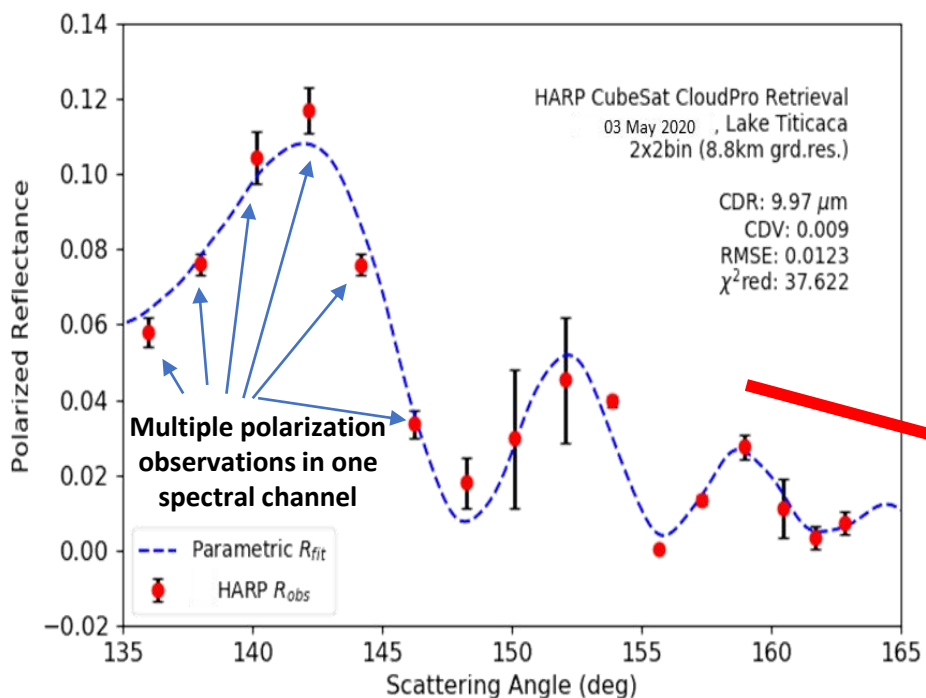
Separate tables for liquid, ice phase clouds

Original concept had a longer wavelength SWIR channel, but study contract indicated this was infeasible

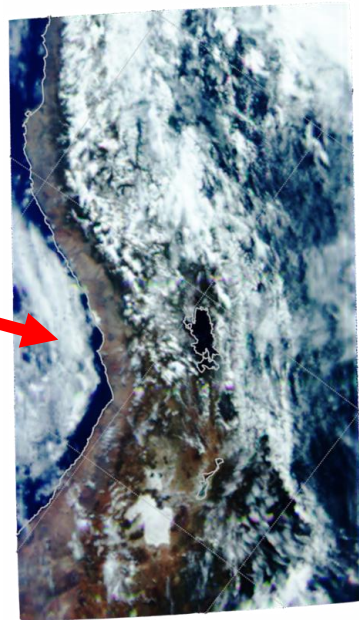
Polarimeter Traceability Matrix: Clouds

The **Rainbow** method uses multi-angle VIS polarization

Example from HARP CubeSat



**Hyperangle (60+),
 polarimetric VIS
 observations**



**Cloud droplet effective radius (GV5)
 Cloud droplet effective variance
 Cloud optical depth (GV7)**

Details:
 Less heritage, but performed with POLDER

Sensitive to top of cloud, less sensitive to 3D impacts, aerosols.

Requires ability to observe at scattering angles > 140°

Ice clouds: different polarimetric approach which doesn't need hyperangle observations

This is also a good way to determine cloud phase

Polarimeter Traceability Matrix: **Aerosols**



Thresholds indicated by [brackets]

Science Objectives	Geophysical Variable Requirements		Observables	Measurements		Instrument			
	Geophysical Variable	Conditions		Requirements	Performance	Projected Performance*	Projected Performance*		
O3. Convective Processes O5. Aerosol attribution and air quality	GV12. Aerosol column optical depth (UV, VIS, NIR) O3, O5, O6, O7, O8	Daytime, clear sky, global [ocean] [UV] VIS-NIR Uncertainty: 0.03+0.1*AOD Resolution: 0.5 [1] km nadir Swath: 300 [100] km	Passive, multi-angle, total and polarimetric radiance [UV] VIS-NIR-SWIR	Daytime measurements of Aerosol optical depth (GV12) Aerosol absorption optical depth (GV13) Aerosol fine mode effective radius (GV14) +other aerosol microphysical properties		Meets/exceeds baseline			
O6. Aerosol removal, vertical redistribution, and processing	GV13. Aerosol column aerosol absorption optical depth (UV, VIS) O5, O6, O7, O8	Daytime, clear sky, global [ocean] [UV] VIS Uncertainty: max(0.003,50%) [max(0.005, 50%)] Resolution: 0.5 [1] km nadir Swath: 300 [100] km				at 500m resolution and 300km swath (baseline)		Meets/exceeds baseline	
O7. Aerosol direct effect and absorption O8. Aerosol indirect effect	GV14. Aerosol column fine-mode effective radius O5, O6, O7, O8	Daytime, clear sky, global [ocean] Uncertainty: max(0.05,0.1*(0.1 ^{AOD})) μm Resolution: 0.5 [1] km nadir Swath: 300 [100] km				important for 5 science objectives		Meets/exceeds baseline	

* Projected performance is for industry study instruments MegaHARP-4 and MegaHARP-2; polarimeter contract will be awarded in Phase-B

Simultaneous retrieval of GV's with radiative transfer model optimization

multiangle, polarimetric
 UV-VIS-NIR observations



Aerosol optical depth (GV12)

Aerosol absorption optical
 depth (GV13)

Aerosol fine mode effective
 radius (GV14)

+other aerosol microphysical
 properties

Radiative transfer simulations are iteratively adjusted until the simulation – measurement 'cost function' is minimized



Benefit from
 PACE algorithm
 development

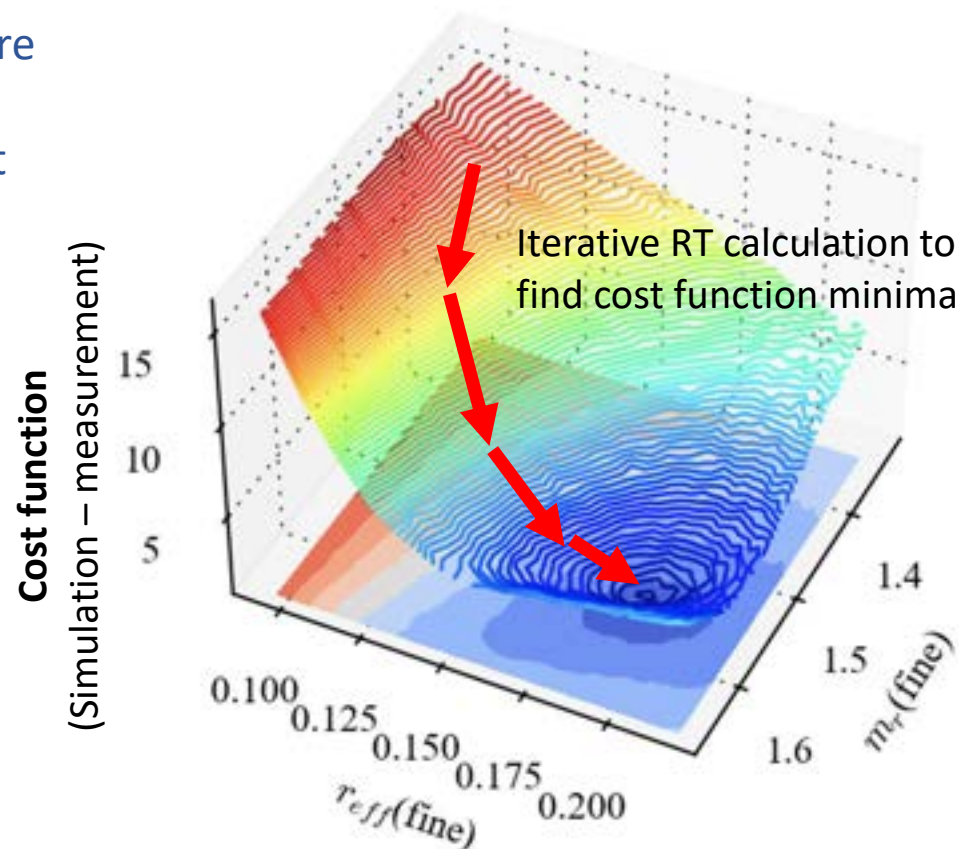
Example Algorithms:

GRASP: 10.5194/essd-12-3573-2020

MAPP: 10.1364/AO.57.002394

RemoTAP: 10.5194/amt-2019-287

fastMAPOL: 10.5194/amt-2020-507



Polarimeter + Lidar Aerosol Synergy

multiangle, polarimetric
 UV-VIS-NIR observations



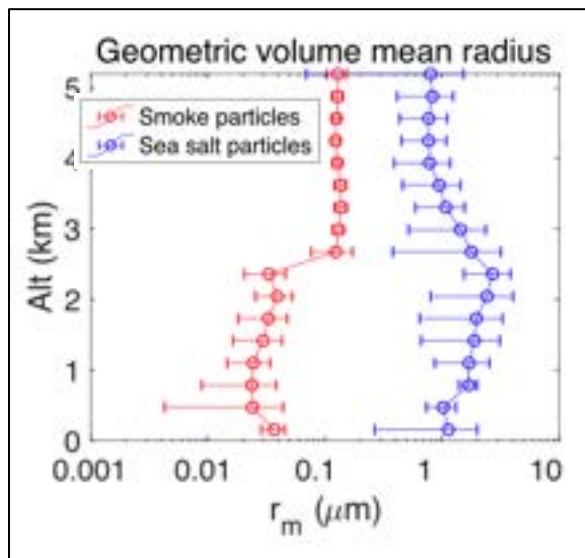
Aerosol optical depth (GV12)
 Aerosol absorption optical
 depth (GV13)
 Aerosol fine mode effective
 radius (GV14)
 + other aerosol microphysical
 properties

With
 Lidar
 synergy

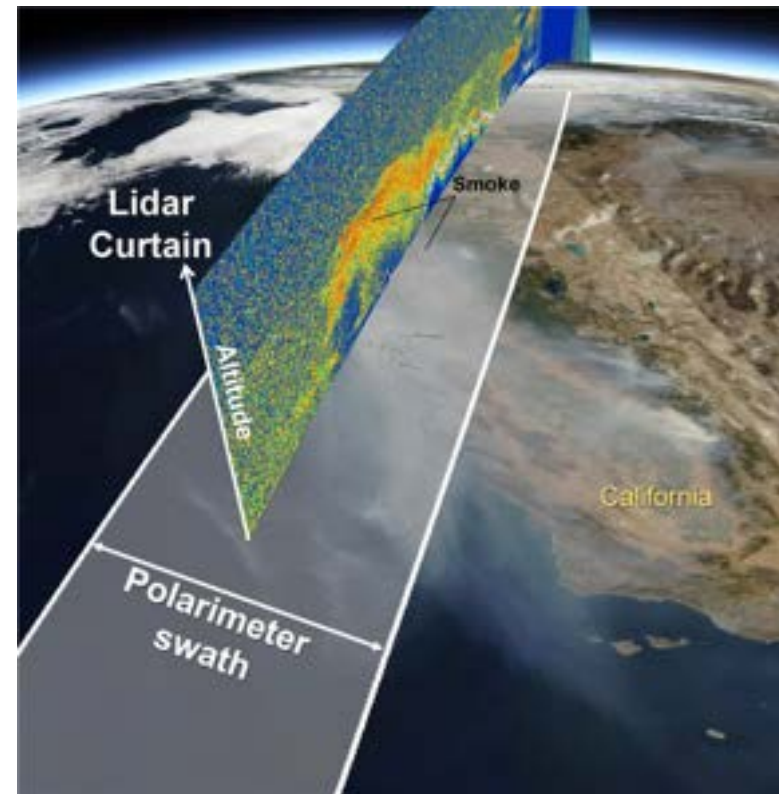


Vertically
 resolved
 micro-
 physical
 properties

Example of one of several
 retrieved parameters in F. Xu et al.
 doi: 10.3389/frsen.2021.620871



+ horizontal context



Summary of RFI responses



Instrument	Class	Mass (kg)	Avg. Power (W) *pk	Dimensions (m)	Orbit avg. data rate (Mbps)	Polarized UV channels	Polarized VIS-NIR channels	Polarized SWIR channels	Hyperang. channels	# views	Swath	Resolution (km)	Rad. Unc.	DoLP Unc.
ACCP Study														
S-Polar01	C	65 (CBE) 80 (MEV)	48	0.7 x 0.9 x 0.5	depends on # targets	-	2	1	-	mechanically gimballed	160	0.132 x 0.124	4%-6%	0.50%
S-Polar02 (a)	C	122	167*	1.5 x 0.9 x 0.9	6.6	-	2	1	-	5	160	0.132 x 0.124	4%-6%	0.50%
S-Polar02 (b)	D	10/camera a + 64	15/camera *	6U for cameras + 0.7x0.9x0.5	1.5/camera	-	2	1	-	5	160	0.132 x 0.124	4%-6%	0.50%
S-Polar03	D	256	400	0.90 x 0.68 x 0.96	20	24	196	-	-	1	300	0.175 x 0.500	5%	0.50%
S-Polar04 (a)	D	6	23	0.10 x 0.20 x 0.17	26.7	2	4	4	1	10 (60)	1130	1	3%	0.50%
S-Polar04 (b)	D	21	23	0.49 x 0.24 x 0.49	26.7	2	4	4	1	10 (60)	1130	1	3%	0.50%
S-Polar04 (c)	D	41	39	0.79 x 0.66 x 0.39	34.6	3	6	6	1	10 (60)	1130	1	3%	0.50%
S-Polar04 (d)	D?	65	48	0.7 x 0.9 x 0.5	6.6	2	4	4	1	10 (60)	1130	1	3%	0.50%
S-Polar05	D?	11 (CBE) 15 (MEV)	20	0.10 x 0.20 x 0.17	26.7	2	4	4	-	5	100	2.3x2.7	2%	0.30%
S-Polar06	C	57.2 (MEV)	73	0.62 x 0.57 x 0.49	0.126	-	6	3	9	255	5.6	5.6	5%	0.20%
S-Polar07	D?	35	46	0.38 x 0.60 x 0.43	55	2	5	4	1	10 (60)	550	0.5	3%	0.50%
S-Polar08	D?	61	51	0.46 x 0.55 x 0.52	60	2	4	6	1	10 (60)	550	0.5	3%	0.50%
S-Polar09	D?	3	10	0.40 x 0.20 x 0.11 (optical)	0.15	1	4	-	-	3	3 x 120km	1	3%	0.30%
Pre-Phase A														
Mega-HARP		35	69.2	0.58 x 0.40 x 0.44	55?	2	4	4	1	10 (60)	344	1?	3%	0.50%
HARP2-UVS		21	34.6	0.24 x 0.49 x 0.48	26.7?	1	4	4	1	10 (60)	861	1	3%	0.50%
EHARP						2	6	7	1	10 (60)			3%	0.50%
EPIC MAP						-	3	2		5		1	3%	0.30%

There was a robust response to early RFIs, but many did not meet needs.

Green: meets baseline requirements

Yellow: Doesn't meet baseline, threshold ok

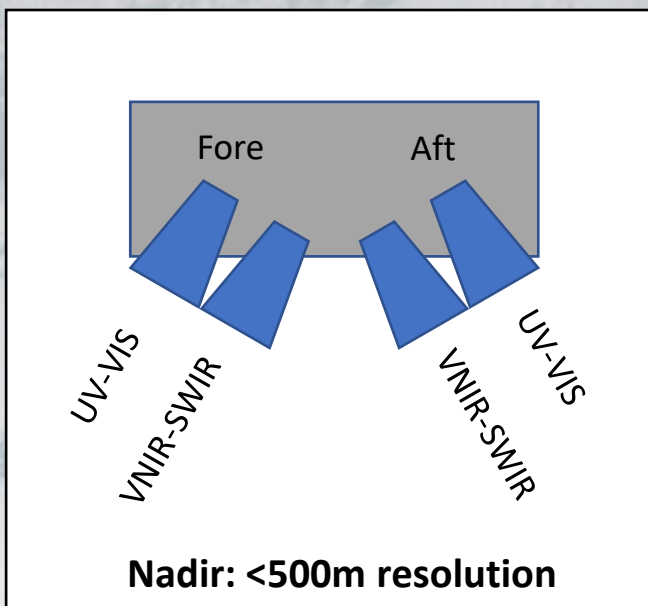
Orange: Doesn't meet threshold

Basis for ACCP study

Concepts in UMBC/SDL polarimeter study (as MegaHARP4, MegaHARP2)

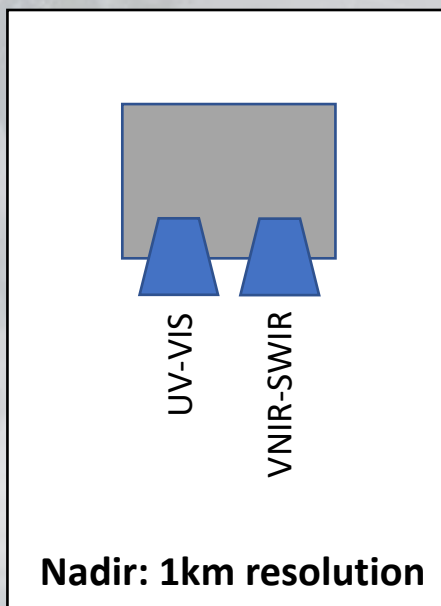
MegaHARP-4

Spatial resolution **baseline**



MegaHARP-2

Spatial resolution **threshold**



Ability to meet requirements is otherwise identical
Geophysical Variable horizontal resolution may vary

MegaHARP uses wide field of view optics, prism based amplitude polarization separation, and linear stripe filters

HARP Prism Polarization Separation

Intensity_{0°}
 Intensity_{45°}
 Intensity_{90°}

Stripe Filters: Angular and Wavelength Separation

Backward
 Nadir
 Forward view

Linearly Polarized Images at 0°, 45° and 90°

HyperAngle Rainbow Polarimeter (HARP) concept

Multi/Hyper Angle with multiple pushbrooms

UMBC **Space Dynamics**
 LABORATORY
 Utah State University

See: Martins, et al. IEEE IGARSS 2018, 6304--6307.

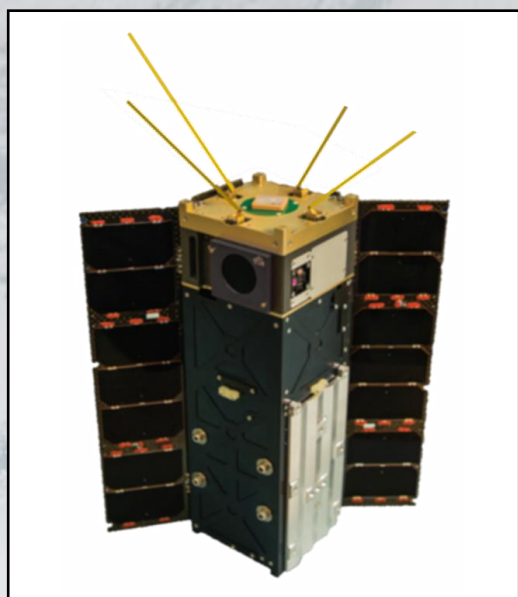
MegaHARP heritage



Heritage: PACE/HARP2 (launch 2024), HARP-Cubesat (recent de-orbit)

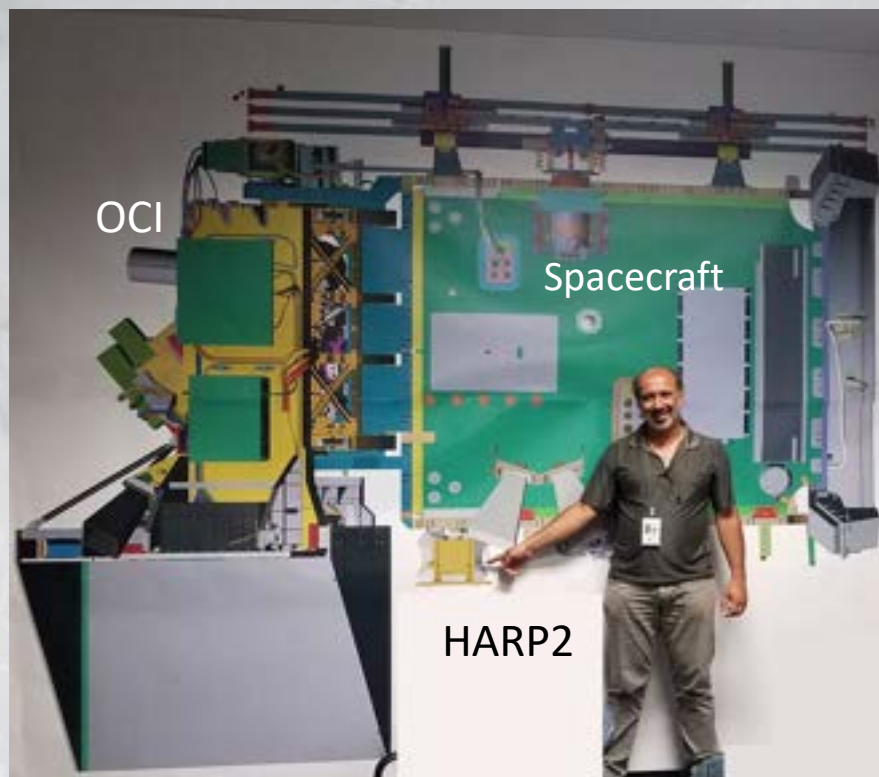
Compared to MegaHARP, these do not have SWIR, have coarser spatial resolution, and less sophisticated calibration mechanisms and less accuracy.

HARP CubeSat



January 2020 – April 2022
4km resolution
No onboard calibrator
Limited downlink
bandwidth, coverage

Plankton, Aerosol, Cloud, ocean Ecosystem (PACE)



pace.gsfc.nasa.gov
Launch in 2024

HARP2 is a
contributed 'do no
harm' instrument

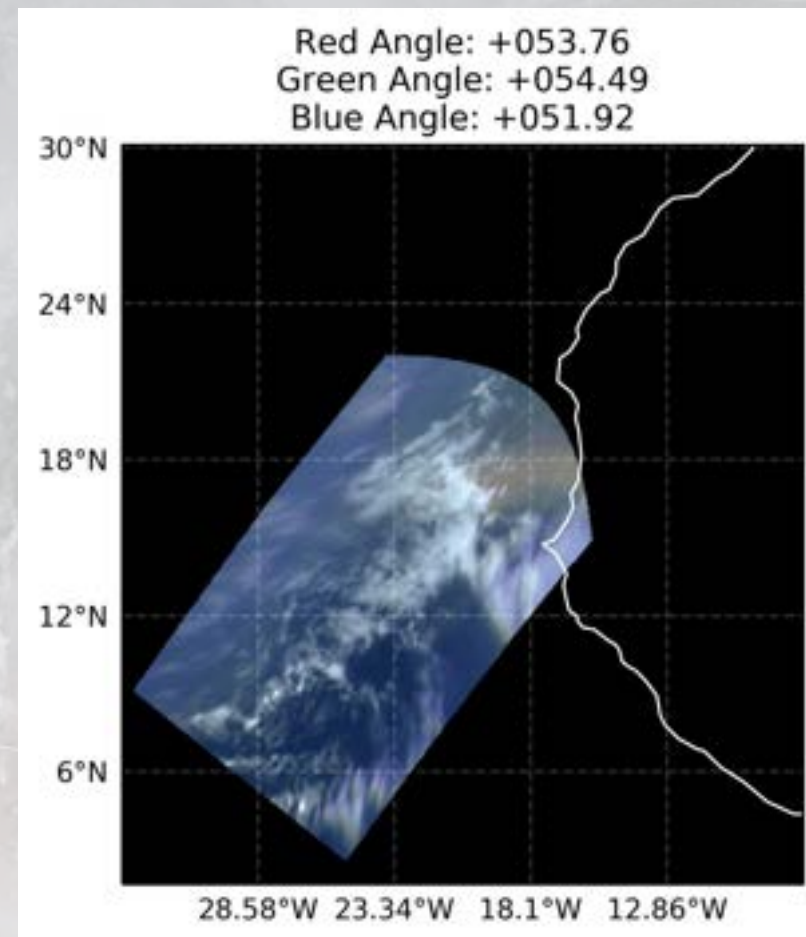
The **AOS-P polarimeter will support all eight science objectives** by making daytime, passive, measurements of cloud and aerosol optical properties in a swath.

RFI material and a pre-phase A study demonstrate the likelihood of **at least one viable RFP response** that can meet requirements. Descope/costing options are included.

The polarimeter, with lidar synergy, will **enable first ever observations** of aerosol property profiles, cloud and aerosol processes and more.

Proposed designs improve upon heritage with better accuracy, spatial resolution and spectral range (UV through SWIR). Overall budget and SWaP is relatively small compared to active instruments.

HARP Cubesat RGB imagery, West Africa with Saharan dust, glint, clouds 2020 / 06 / 13



Extra material

Polarimeter Traceability Matrix: Clouds



Thresholds indicated by [brackets]

Science Objectives	Geophysical Variable Requirements		Observables	Measurements		Instrument	
	Geophysical Variable	Conditions		Requirements	Projected Performance*	Requirements	Projected Performance*
O1. Low Clouds O2. High Clouds O4. Cold clouds and precipitation	GV5. Cloud droplet effective radius O1, O6, O8	Daytime , low cloud (<5km top) Uncertainty: 50% for precipitating clouds, 20% otherwise Range: optical depth > 2, effective radius 5-30µm Resolution: 500m [1km] nadir Swath: 300km [100km]	Passive bi-spectral (NIR, SWIR) radiance pairs -- OR --	Bispectral method	Spectral: 1 NIR, 1 SWIR at 1600 nm UV-VIS: 380, 410, 550, 660 NIR-SWIR: 870, 940, 1230, 1380, 1570 Exceeds baseline	Resolution: 500m [1km] at nadir Meets baseline MegaHARP-2: 1km Meets threshold	
					View angles: 1 (nadir) 10 view angles within ± 57° along track for all channels except 660nm, which has 60 exceeds baseline	Swath: 300km [100km] Exceeds baseline MegaHARP-4: 394km MegaHARP-2: 1008km Exceeds baseline	
					Uncertainty: 3% radiometric Meets baseline	3% radiometric Meets baseline	
O6. Aerosol removal, vertical redistribution, and processing O8. Aerosol indirect effect	GV7. Cloud optical depth O1, O2, O4, O6, O8	Daytime Uncertainty: max(0.3, 50%) Range: 0.3 < optical depth < 50 Resolution: 1km nadir	Passive hyper-angle VIS polarization in one channel	Rainbow method	Spectral: 1 NIR hyper-angle NIR hyperangle: 660 meets baseline	Resolution: 500m [1km] at nadir Meets baseline MegaHARP-2: 1km Meets threshold	
					View angles: 60 within ± 57° along track 60 view angles within ± 57° along track for 660nm channel meets baseline	Swath: 300km [100km] Exceeds baseline MegaHARP-4: 394km MegaHARP-2: 1008km Exceeds baseline	
					Uncertainty: 3% radiometric, 0.005 DoLP polarimetric Meets/exceeds baseline	3% radiometric, 0.003 DoLP polarimetric Meets/exceeds baseline	

* Projected performance is for industry study instruments MegaHARP-4 and MegaHARP-2; polarimeter contract will be awarded in Phase B

Polarimeter Traceability Matrix: Aerosols



Thresholds indicated by [brackets]

Science Objectives	Geophysical Variable Requirements		Observables	Measurements		Instrument	
	Geophysical Variable	Conditions		Requirements	Projected Performance*	Requirements	Projected Performance*
O3. Convective Processes O5. Aerosol attribution and air quality O6. Aerosol removal, vertical redistribution, and processing O7. Aerosol direct effect and absorption O8. Aerosol indirect effect	GV12. Aerosol column optical depth (UV, VIS, NIR) O3, O5, O6, O7, O8	Daytime, clear sky, global [ocean] [UV] VIS-NIR Uncertainty: 0.03+0.1*AOD Resolution: 0.5 [1] km nadir Swath: 300 [100] km	Passive, multi-angle, total and polarimetric radiance for [UV] VIS-NIR-SWIR	Spectral: 1 UV, 3 VIS-NIR, 3[2] SWIR to 2250 [1600] nm	UV-VIS: 380, 410, 550, 660 NIR-SWIR: 870, 940, 1230, 1380, 1570 UV meets baseline VIS-NIR exceeds baseline SWIR meets baseline in # of channels, threshold in range	Resolution: 500m [1km] at nadir	MegaHARP-4: 0.5km Meets baseline MegaHARP-2: 1km Meets threshold
	GV13. Aerosol column aerosol absorption optical depth (UV, VIS) O5, O6, O7, O8	Daytime, clear sky, global [ocean] [UV] VIS Uncertainty: max(0.003,50%) [max(0.005, 50%)] Resolution: 0.5 [1] km nadir Swath: 300 [100] km					
	GV14. Aerosol column fine-mode effective radius O5, O6, O7, O8	Daytime, clear sky, global [ocean] Uncertainty: max(0.05,0.1*(0.1 ^{AOD})) μm Resolution: 0.5 [1] km nadir Swath: 300 [100] km		Uncertainty: 3% radiometric, 0.003 DoLP polarimetric 0.005 DoLP polarimetric	3% radiometric, 0.003 DoLP polarimetric Meets/exceeds baseline		

* Projected performance is for industry study instruments MegaHARP-4 and MegaHARP-2; polarimeter contract will be awarded in Phase-B